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Dr. Paul Rispin, Program Manager Office of Naval Research, Code 331 875 North Randolph Street, Room 273 Arlington, VA 22203-1995

Subject: Deliverable Number 0015, Collaborative Toolkit System Documentation

and User Manual: The TRANSWAY Toolset for Adaptive Planning

Reference: Strategic Mobility 21 Contract N00014-06-C-0060

Dear Paul,

In accordance with the requirements of referenced contract, we are pleased to submit this Collaborative Toolkit System Documentation and User Manual: The TRANSWAY Toolset for Adaptive Planning for your review.

Your comments on this document are welcomed.

Regards,

Dr. Lawrence G. Mallon

Strategic Mobility 21 Program Manager

cc: Administrative Contracting Officer (Transmittal Letter only)

Director, Naval Research Lab (Hardcopy via U.S. Mail)

Defense Technical Information Center

Stan Wheatley



Strategic Mobility 21

Collaborative Toolkit System Documentation & User Manual:

The TRANSWAY Toolset for Adaptive Planning

Contractor Report 0015

Prepared for:

Office of Naval Research 875 North Randolph Street, Room 273 Arlington, VA 22203-1995

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In fulfillment of the requirements for:

FY 2005 Contract No. N00014-06-C-0060 Strategic Mobility 21 – CLIN 0015

Prepared and Submitted by:

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November 30, 2006

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Abstract

This report describes the capabilities of the TRANSWAY suite of tools in the logistical domain. It addresses in particular their suitability for supporting an end-to-end military deployment exercise that is scheduled to occur within the Southern California public transportation corridor sometime in the first half of 2007. In support of this planned exercise the ontology-based intelligent agents of the TRANSWAY adaptive toolset will be able to assist operators in the planning and re-planning of delivery plans along alternative surface routes and air channels within a geo-spatial reference frame.

TRANSWAY User Guide

Executive Summary Description

Background: The deployment and distribution responsibilities of USTRANSCOM call for intelligent collaborative tools in support of strategic and operational planning functions involving the sustainment and movement of forces. The sustainment requirement is generated at the operational level and is dynamic. It is composed of shifting priorities responding to changes in commander's intent and changes in the operational situation. However, while commander's intent and future plans normally drive the sustainment requirement, it is also possible for the reverse to occur. Unit movement and sustainment flow planning and execution monitoring is largely planned and executed at the strategic level, responding to ship and aircraft availability and other gross transportation factors only indirectly related to the changing operational priorities in the theater. Strategic flow planning and execution processes are focused on logistic efficiency and tonnage, while satisfying operational requirements is focused on logistic effectiveness (i.e., providing the right thing in the right quantity at the right place at the right time to the right units).

Functional Capabilities: TRANSWAY is designed as a set of intelligent collaborative tools supporting operators performing planning and re-planning tasks in a dynamically changing decision-making environment. The open, service-oriented architecture of TRANSWAY allows these capabilities to be progressively extended, to include:

- Intelligent decision-support tools that detect changing sustainment priorities and automatically generate options that integrate transport assets, inventory availability, and on-going operations.
- Intelligent decision-support tools that are capable of integrating theater infrastructure capacities and characteristics (as well as changes to these) into sustainment and distribution plans, and projections.
- Intelligent decision-support tools that ensure continuous visibility of both the dynamic sustainment requirements and the strategic sustainment plans generated in response to these requirements.

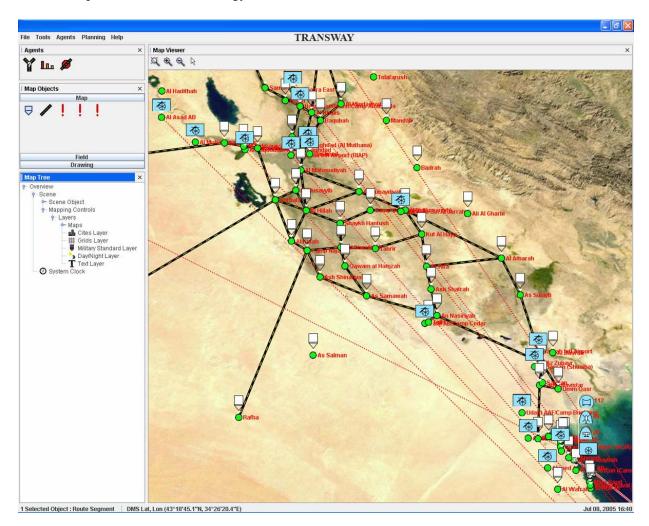
Underlying Ontology: The TRANSWAY ontology is divided into logical domains that can be described using the Unified Modeling Language (UML) methodology. Within each domain exist definitions of the various concepts and entities relevant to the representation and analysis of key aspects of each domain. Classes located within package symbols are defined within that domain. These classes may relate to classes defined in other domains through either inheritance or associations. In both cases, referenced classes are identified by their symbols existing outside the primary package symbol with some type of relationship symbol connecting them to package elements. Domains themselves may be related to each other in either a sibling or parent/child relationship. Such connections are an indication of the particular scope and inter-domain visibility.

Intelligent Agents: TRANSWAY includes two kinds of agents with strategic and operational planning and re-planning capabilities, respectively. The strategic planning agents are based on the Tabu genetic search algorithm and the operational planning agents are rule-based and implemented in Java.

Tabu Search is a local search method for exploring a solution space. In the TRANSWAY implementation of the Tabu genetic algorithm the solution space is every possible planning recommendation. Starting from an initial empty plan, new plans are generated and immediately evaluated based on a merit function. The highest rated plan then becomes the new incumbent best solution, followed by a repetition of the same procedure. Once some ending criterion has been reached the algorithm may stop and report the best

solution that it has found or, as in the current version of TRANSWAY, reporting may occur on a continuous basis as better and better solutions are found.

The Re-Planning Agent prepares plans for the delivery of cargo to the required destinations and re-plans when necessary. It makes use of the ICDM-Hibernate library in order to be a collaborative component of the TRANSWAY system. Planning and re-planning sequences proceed in three basic steps, as follows: (1) extraction of the current problem domain model from the ontology; (2) preparation of a solution plan that does not violate any of the logistical constraints; and, (3) injection of the problem domain model of the solution plan back into the ontology.



Development Stage: The development of TRANSWAY commenced in October 2004 under sponsorship of USTRANSCOM (J6). An initial test-bed application environment was demonstrated in April 2005. TRANSWAY Version 1 is scheduled for delivery with a web-based user-interface and subsequent field testing in December 2006.

Further Information: Jens Pohl, CTO CDM Technologies, Inc. (805-756-2841; jpohl@cdmtech.com)

Comprehensive TRANSWAY Scenario

The main TRANSWAY screen (Figure 1) is divided into two principal areas. On the left side, moving from the top down, below the main option bar the user will find: three agent icons; objects that may be placed on top of the map (the right side of the screen); a tree-structure that provides quick and convenient access to the data that the system is currently populated with; and, at the bottom a command window for the Tabu agent. On the right side of the screen is a geo-referenced map that allows the user to pan to any part of the world and, subject to the availability of maps, zoom down to street level if desired. Objects representing nodes (e.g., SAAS, APODS, etc.), route segments, impediments, and areas of interest may be moved from the left side of the screen to the right side by simple *click to locate* actions. Alternatively, the user may specify latitude-longitude locations and the selected object will be automatically placed on the map in the correct location. These objects, whether entered by the user or pre-initialized in the system, have attributes that relate to TRANSWAY's internal ontology and provide the necessary context for automated agent actions.

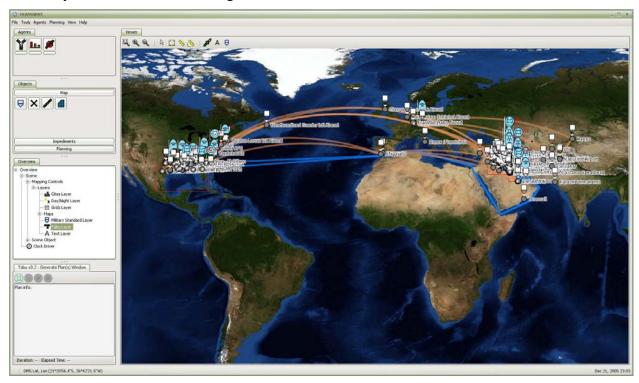


Figure 1: Main TRANSWAY screen

TRANSWAY is by no means limited to the current set of attributes. With the contractual goal of this first version of a prototype system to demonstrate the typical capabilities of an ontology-based multi-agent system, attributes were selected in a fairly generic fashion based on the feedback that the development team received during early demonstrations, perusal of military documents, and in-house experience with other logistic planning systems such as the Integrated Computerized Deployment System (ICODES) and the Joint Forces Collaborative Toolkit (JFCT).

| 0 | | | | | | | | - | |
|----------------------------------|-------------|-------------|------------|--|--|-------------|---------|----------|---|
| Supply Center Summary | | | | | | | | | |
| | | | | | | | | | |
| Supply Center | MOG Parking | MOG Working | Throughput | The state of the s | State of the state | Rotary Wing | Vessels | Vehicles | |
| Charleston AFB | 15 | 10 | 0.0 | 0.5000000000000000000000000000000000000 | 15 | 0 | 8 | 0 | 2 |
| Dover AFB | 15 | 10 | 0.0 | A Plantage 1 | 14 | 0 | 0 | 0 | |
| Ramstein AFB | 15 | 10 | 0.0 | | 17 | 0 | 0 | 0 | |
| Ash Shuaybah | 20 | 10 | 0.0 | | 0 | 0 | 0 | 24 | |
| (uwait Intl Airport (KCIA) | 6 | 5 | 0.0 | 966.1 | 4 | 5 | 0 | 20 | |
| Al Taqaddum AB | 2 | 2 | 0.0 | 966.1 | 0 | 4 | 0 | 10 | |
| Al Udeid AB | 2 | 2 | 0.0 | 966.1 | 8 | 5 | 0 | 0 | |
| Bagram AB | 2 | 2 | 0.0 | 966.1 | 0 | 0 | 0 | 0 | |
| Balad Southeast/Camp Anaconda | 2 | 2 | 0.0 | 966.1 | 1 | 7 | 0 | 16 | |
| Candahar | 2 | 2 | 0.0 | 966.1 | 0 | 0 | 0 | 0 | |
| Barksdale AFB | 15 | 10 | 0.0 | 432.5 | 7 | 0 | 0 | 0 | |
| OTF Katrina - Ft Gillem | 10 | 6 | 0.0 | 432.5 | 7 | 0 | 0 | 0 | |
| (elly/Lackland | 10 | 6 | 0.0 | 432.5 | 7 | 0 | 0 | 0 | |
| ort Worth NAS | 15 | 6 | 0.0 | 432.5 | 7 | 0 | 0 | 0 | |
| Jacksonville NAS | 0 | 0 | 0.0 | | 0 | 0 | 6 | 0 | |
| Dallas-FT Worth IAP | 15 | 10 | 0.0 | | 0 | 0 | 0 | 0 | U |
| England AFB | 15 | 10 | 0.0 | 12.522 | 0 | 0 | 0 | 0 | |
| George Bush IAP | 15 | 10 | 0.0 | 202 | 0 | 0 | 0 | 0 | |
| Glasgow Prestwick Airport | 15 | 10 | 0.0 | D. 5000 | 0 | 0 | 0 | 0 | |
| JFK | 15 | 10 | 0.0 | 505 | 0 | 0 | 0 | 0 | |
| Maxwell AFB | 15 | 10 | 0.0 | 2.000 | 0 | 0 | 0 | 0 | |
| Newfoundland Gander Intl Airport | 15 | 10 | 0.0 | 2.000 | 0 | 0 | 0 | 0 | |
| Tvdall AFB | 15 | 10 | 0.0 | 2000 | 0 | 0 | 0 | 20 | |
| Mobile Regional AP | 10 | 6 | 0.0 | 7.57 | 0 | 0 | 0 | 20 | |
| NAS Meridian | 10 | 6 | 0.0 | | 0 | 0 | 0 | 0 | |
| Rota NAS | 10 | 6 | 2.333 | 7.77 | 0 | 0 | 0 | 0 | |
| | 47.5 | | 0.0 | 202 | | | | | |
| William P. Hobby | 10 | 6 5 | 0.0 | | 0 | 0 | 0 | 0 | |
| Camp Najaf | 10 | 20 | 0.0 | 7.535 | 0 | 0 | 0 | 51 | |
| Camp Navistar | 10 | 5 | 0.0 | 7.535 | 0 | 0 | 0 | 0 | |
| Camp Scania (An Numanlyh) | 10 | 5 | 0.0 | 2.000 | 0 | 0 | 0 | 0 | |
| ouis Armstrong IAP | 0 | 4 | 0.0 | 202 | 0 | 0 | 0 | 0 | |
| Al Asad AB | 5 | 3 | 0.0 | 2.55 | 0 | 0 | 0 | 0 | |
| Baton Rouge Metro | 5 | 3 | 0.0 | | 0 | 0 | 0 | 20 | |
| Ellington, TX | 5 | 3 | 0.0 | 7.57 | 0 | 0 | 0 | 0 | |
| Gulf Port IAP | 5 | 3 | 0.0 | 2.33 | 0 | 0 | 0 | 0 | |
| ITF FWD - Camp Shelby | 5 | 3 | 0.0 | 7. CO. | 0 | 0 | 0 | 20 | |
| Carshi | 5 | 3 | 0.0 | 2.323 | 0 | 0 | 0 | 0 | |
| afayette IAP | 5 | 3 | 0.0 | 535 | 0 | 0 | 0 | 20 | |
| Manas | 5 | 3 | 0.0 | 75.535 | 0 | 0 | 0 | 0 | |
| Thumrait | 5 | 3 | 0.0 | 0.0 | 0 | 0 | 0 | 0 | |
| (essler AFB | 0 | 2 | 0.0 | 0.0 | 0 | 0 | 0 | 0 | |
| Al Sahra AB/Camp Speicher | 3 | 2 | 0.0 | | 0 | 0 | 0 | 0 | |
| Al Qayyarah West | 4 | | 0.0 | 0.0 | 0 | 0 | 0 | 0 | |
| Herat | 4 | 2 | 0.0 | 0.0 | 0 | 0 | 0 | 0 | |
| Kirkuk AB | 4 | 2 | 0.0 | | 0 | 4 | 0 | 0 | |
| Mosul AB/Camp Diamondback | 4 | 2 | 0.0 | 0.0 | 0 | 0 | 0 | 0 | |
| Fallil AB/Camp Cedar | 4 | 2 | 0.0 | C-0000 | 0 | 0 | 0 | 0 | |
| Ali Al Salem AB | 2 | i | 0.0 | 2.333 | 0 | 0 | 0 | 0 | |
| Baghdad Intl Airport (BIAP) | 2 | 1 | 0.0 | 73 SSSS | 2 | 8 | 0 | 20 | |
| (abul Intl Airport | 4 | 1 | 0.0 | 72.222 | 0 | 0 | 0 | 0 | |
| Ad Diwaniyah | 0 | 0 | 0.0 | 2.000 | 0 | 0 | 0 | 0 | ſ |
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Figure 2: Summary of supplies and available conveyances at supply centers

The report shown in Figure 2 provides a summary of supplies (short tons) and available conveyances (i.e., fixed wing aircraft, helicopters, ships, and trucks (in convoys)) at most supply centers currently initialized in the system for this particular demonstration scenario. Details of supplies at Charleston and Al Udeid are shown in Figures 3 and 4 (in terms of supply Class, number of pallets, number of items per pallet, and short tons), respectively.

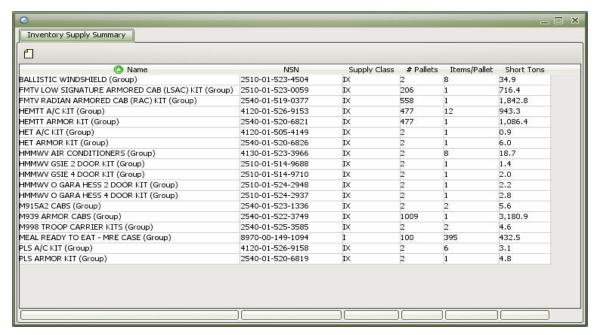


Figure 3: Details of supplies at Charleston

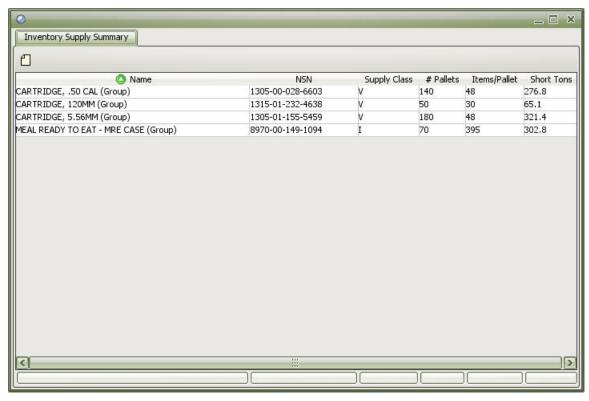


Figure 4: Details of supplies at Al Udeid

| First Location Ash Shuaybah Ash Shuaybah | Second Location | | | |
|--|----------------------------------|--------------|-------------------|--------|
| Ash Shuaybah | Second Location | | | |
| Ash Shuaybah | | Distance | Туре | |
| | Jacksonville NAS | 9,136 n.mi | Sea Surface Track | - 6 |
| | Charleston AFB | 8,943 n.mi | Sea Surface Track | |
| Charleston AFB | Rota NAS | 3,546.7 n.mi | Air Channel | \neg |
| Dover AFB | Ramstein AFB | 3,437.7 n.mi | Air Channel | \neg |
| Charleston AFB | Glasgow Prestwick Airport | 3,327.1 n.mi | Air Channel | \neg |
| JFK | Ramstein AFB | 3,319.7 n.mi | Air Channel | \neg |
| Dover AFB | Rota NAS | 3,194.1 n.mi | Air Channel | - |
| Glasgow Prestwick Airport | Al Udeid AB | 3,024.6 n.mi | Air Channel | \neg |
| Rota NAS | Al Udeid AB | 3,003.9 n.mi | Air Channel | - |
| Dover AFB | Glasgow Prestwick Airport | 2,903.5 n.mi | Air Channel | - |
| Ramstein AFB | Bagram AB | 2,791 n.mi | Air Channel | - |
| Candahar | Ramstein AFB | 2,788 n.mi | Air Channel | - |
| Rota NAS | Kuwait Intl Airport (KCIA) | 2,735.1 n.mi | Air Channel | - |
| Glasgow Prestwick Airport | Kuwait Intl Airport (KCIA) | 2,720.4 n.mi | Air Channel | - |
| Manas | Ramstein AFB | 2,708.9 n.mi | Air Channel | - |
| Ramstein AFB | Al Udeid AB | 2,494.7 n.mi | Air Channel | - |
| Rota NAS | Balad Southeast/Camp Anaconda | 2,459.8 n.mi | Air Channel | - |
| Newfoundland Gander Intl Airport | Ramstein AFB | 2,366.7 n.mi | Air Channel | - |
| Ramstein AFB | Kuwait Intl Airport (KCIA) | 2,193,2 n.mi | Air Channel | |
| Ramstein AFB | Baghdad Intl Airport (BIAP) | 1,887.6 n.mi | Air Channel | - |
| Balad Southeast/Camp Anaconda | Ramstein AFB | 1,865.4 n.mi | Air Channel | - |
| Charleston AFB | Newfoundland Gander Intl Airport | 1,490.6 n.mi | Air Channel | - |
| Charlescon AFB Candahar | Manas | 805.4 n.mi | Air Channel | - |
| Al Udeid AB | Mosul AB/Camp Diamondback | 791.8 n.mi | Air Channel | - |
| Al Udeid AB | Al Qayyarah West | 765.9 n.mi | Air Channel | |
| Al Udeid AB | Kirkuk AB | 717.8 n.mi | Air Channel | |
| Charleston AFB | Barksdale AFB | 687.7 n.mi | Air Channel | |
| Charleston AFB | England AFB | 642.1 n.mi | Air Channel | - |
| Al Udeid AB | | | Air Channel | - |
| Al Udeid AB | Balad Southeast/Camp Anaconda | 641.5 n.mi | | - |
| Al Udeid AB | Al Taqaddum AB | 637.2 n.mi | Air Channel | - |
| | Baghdad Intl Airport (BIAP) | 613.1 n.mi | Air Channel | - |
| Charleston AFB | JFK AB | 553.5 n.mi | Air Channel | - |
| Manas | Bagram AB | 543.9 n.mi | Air Channel | - |
| Al Udeid AB | Thumrait | 472 n.mi | Air Channel | - |
| (irkuk AB | Ali Al Salem AB | 400.9 n.mi | Air Channel | _ |
| Al Asad AB | Ali Al Salem AB | 371.9 n.mi | Air Channel | |
| (elly/Lackland | Lafayette IAP | 346.4 n.mi | Air Channel | |
| Charleston AFB | Tydall AFB | 330.4 n.mi | Air Channel | |
| Ali Al Salem AB | Al Udeid AB | 324.6 n.mi | Air Channel | |
| Maxwell AFB | Charleston AFB | 323.1 n.mi | Air Channel | |
| Fort Worth NAS | Lafayette IAP | 318.9 n.mi | Air Channel | |
| Dallas-FT Worth IAP | Lafayette IAP | 304.9 n.mi | Air Channel | |
| Al Udeid AB | Kuwait Intl Airport (KCIA) | 304.4 n.mi | Air Channel | |
| JTF Katrina - Ft Gillem | JTF FWD - Camp Shelby | 285.4 n.mi | Air Channel | |
| Bagram AB | Karshi | 283 n.mi | Air Channel | |
| Candahar | Bagram AB | 268.3 n.mi | Air Channel | |
| < j | | | | > |

Figure 5: Summary report of air channels and sea routes

Figure 5 provides information about the air channels and sea routes that the system has been initialized with for this particular demonstration scenario. In each case the two end-points and the distance in nautical miles is indicated.

Detailed information about the current compliment of conveyances can be obtained by selecting the appropriate report. Typical examples for various fixed wing aircraft, trucks and ships are shown in Figures 6 to 11, below. The reason that the *speed* and *bearing* attributes in each table are zero is because the conveyances are not currently in-transit.

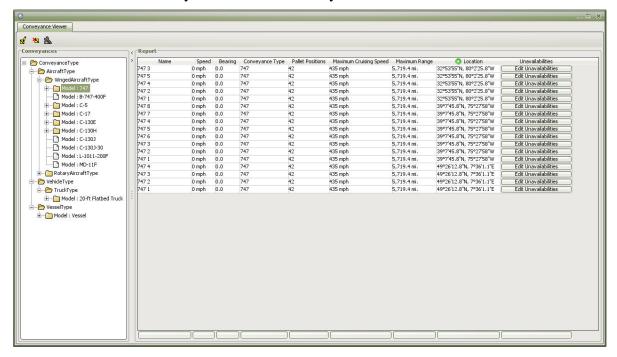


Figure 6: Boeing 747 aircraft attributes

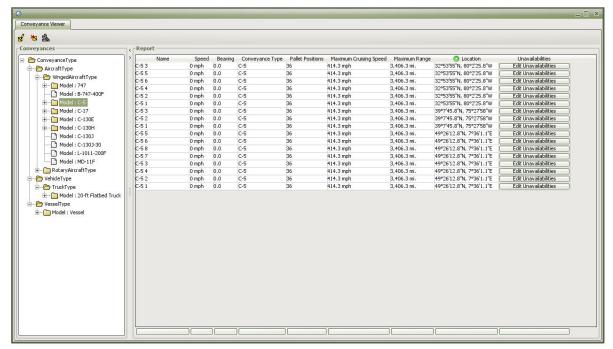


Figure 7: C5 aircraft attributes

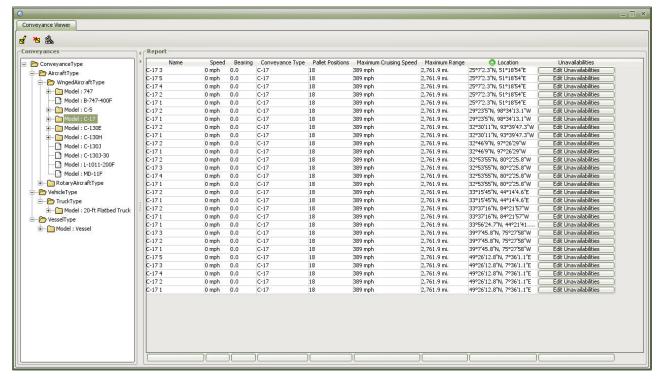


Figure 8: C17 aircraft attributes

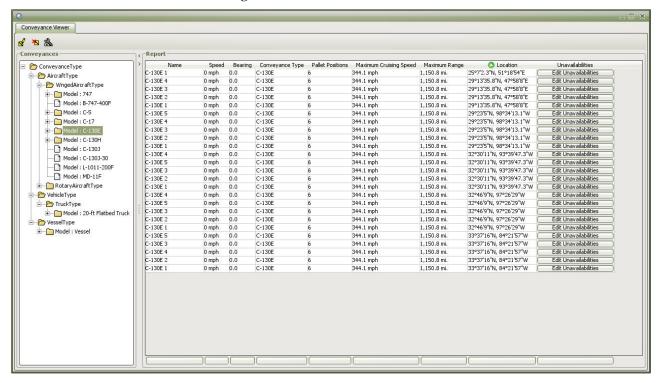


Figure 9: C130 aircraft attributes

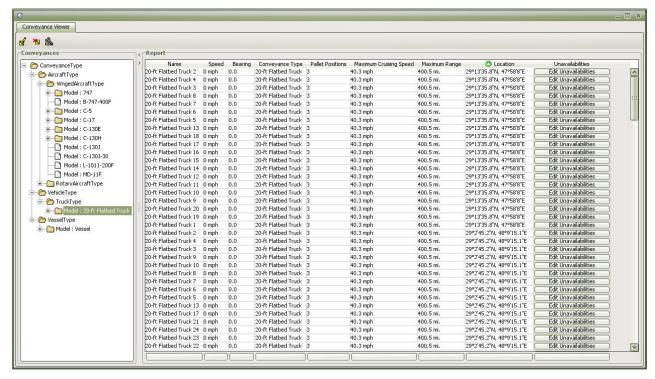


Figure 10: Truck convoy attributes

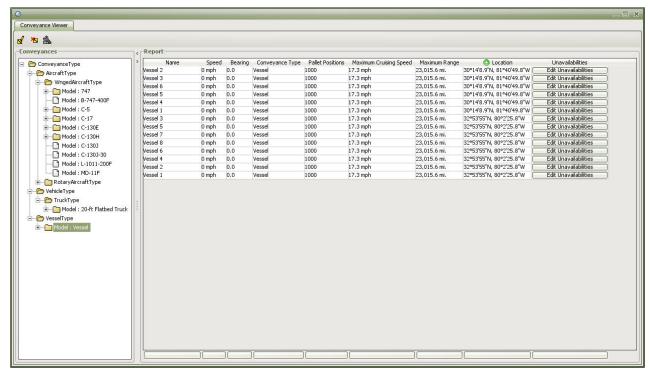


Figure 11: Typical ship attributes

A typical request for *add on armor* is shown in Figure 12. It requires deliver to Al Udeid, with a *high* priority and an earliest and latest time for delivery window of 25 to 31 December 2005.

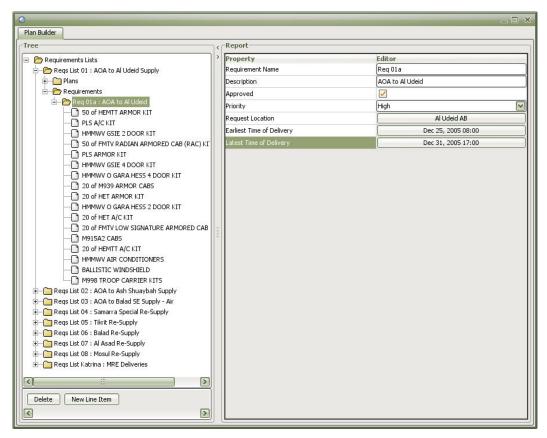


Figure 12: Add-on-Armor (AOR) request for delivery to Al Udeid



Figure 13: User zooms in on map to reduce clutter

| | | × |
|-------------------------------|--|---|
| Property | Editor | |
| Onload Time | 1 days | |
| Offload Time | 1 days |] |
| Earliest Plan Commencem | 4 days | |
| Number of Trucks Per Con | 20 | V |
| R R R R R | eqs List 01 eqs List 02 eqs List 03 eqs List 04 eqs List 05 eqs List 06 eqs List 07 eqs List 08 s List Katrina | |



Figure 14: Tabu agent interface

Figure 15: Control of search duration

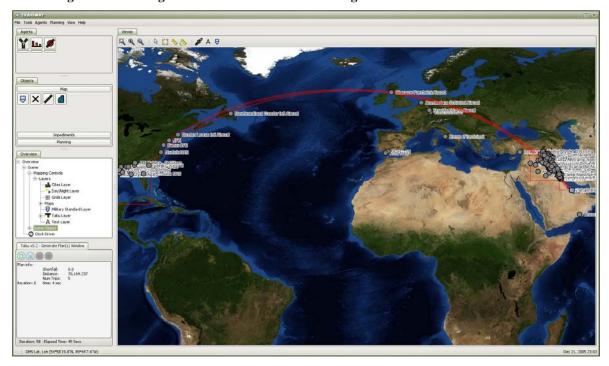


Figure 16: Completed first plan showing routes

To fulfill the request for the shipment of *add-on-armor* to Al Udeid (Figure 12) the user activates the Tabu agent and selects the appropriate *requirement* from the displayed Requirement Lists (Figure 14). In this case the Al Udeid *requirement* is Requirement List 1. Since the Tabu agent has the ability to continue its search for optimum delivery plan even after it has found a way of satisfying the *requirement*, the user has the option of either setting a maximum time for the

planning activity (Figure 15) or allowing the agent to continue until all alternatives have been explored. Of course it is not expected that the user would ever want to wait for that length of time and therefore the option for the user to simply stop the agent is available. versions future of TRANSWAY. particularly if the Tabu agent were to be implemented in an opportunistic mode (i.e., in a manner that would activate the planning process without user involvement as soon as the conditions on which an existing plan were originally based have changed), it would be a relatively simple matter to restrict the extensiveness of the search for an optimum plan. For example, the search could be automatically aborted if after either a specified period of time or a given number of generated plans no better plan has been found.



Figure 3.17: Weather impediment

Figure 17: Weather Implement

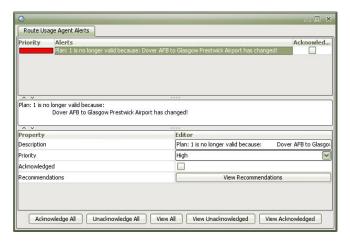


Figure 18: Impediment agent alert

For the completed plan the route is shown in Figure 16 by means of a red line. Next the user enters an impediment in the form of an adverse weather report that essentially eliminates Glasgow as a refueling stop (Figure 17). Immediately, the Impediment agent alerts the user and suggests that re-planning is in order (Figure 18). Again, also in the case of impediments, this first

version of TRANSWAY provides only one type of generic impediment (i.e., a weather condition), with the objective of demonstrating the kinds of causes that would require re-planning that could be easily implemented in subsequent versions of the system, based on user preferences and priorities.

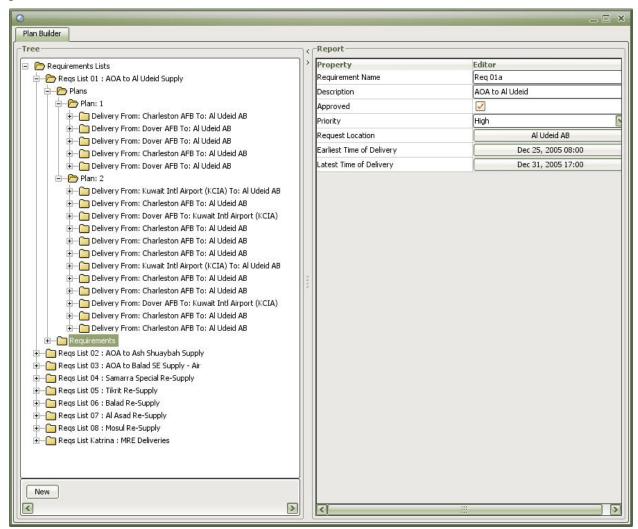


Figure 19: Summary of deliveries for the first and second plans

To initiate a re-planning action the user proceeds in the same manner as described previously for the generation of the first plan (Figures 14 to 16). The user will notice that during the generation of each plan the routes that are being explored by the Tabu agent are dynamically indicated on the map display. Temporarily displayed green lines indicate drop-off points that are being considered. Red lines indicate actual delivery routes with the thickness of the red line providing a proportional indication of the volume of supplies being transported along that particular route. Summary lists of the deliveries involved in both plans are shown in Figure 19.

Even thought this first test-bed version of TRANSWAY is purposely limited in scope it does allow the user to explore the details of each delivery plan (i.e., start and end locations, conveyances and routes used, start and end times, and duration of each trip), as shown in Figures 20 to 23.

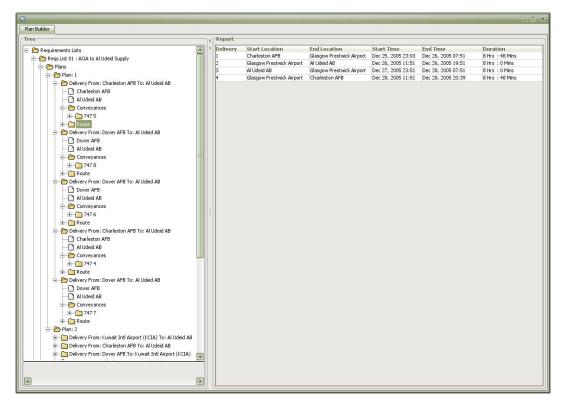


Figure 20: Typical drill-down details of the first plan

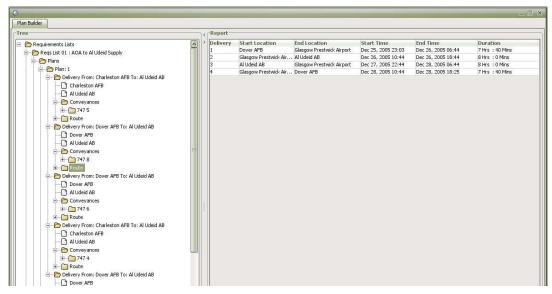


Figure 21: Typical drill-down details of the first plan

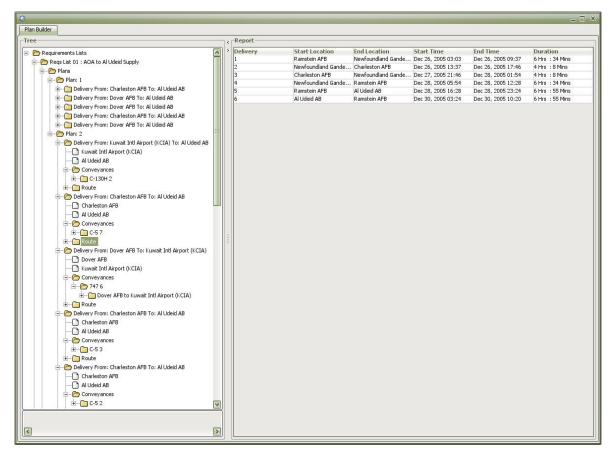


Figure 22: Typical drill-down details of the second plan

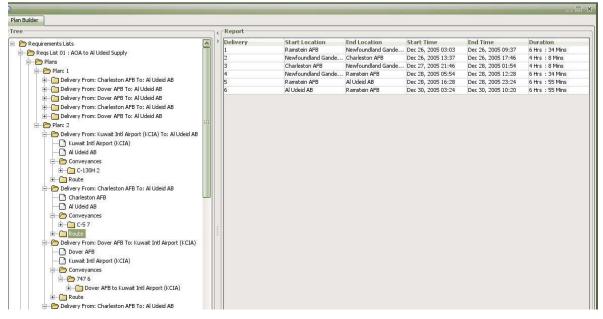


Figure 23: Typical drill-down details of the second plan

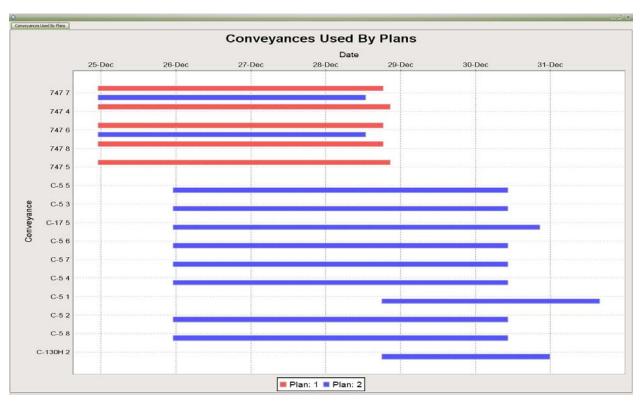


Figure 24: Comparison of conveyances needed in support of the first and second plans

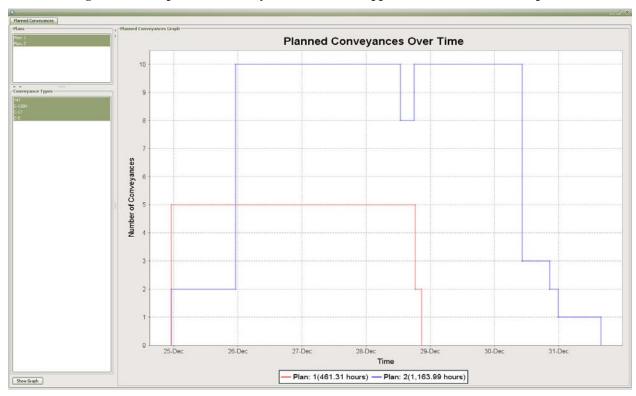


Figure 25: Comparison of overall lift requirements for the first and second plans

Apart from the ability of the user to drill down into the details of each delivery plan there are a number of comparative graphical reports available, such as the utilization of specific

conveyances by each plan shown in Figure 24 and the number of conveyances that are required to support each plan over time shown in Figure 25.

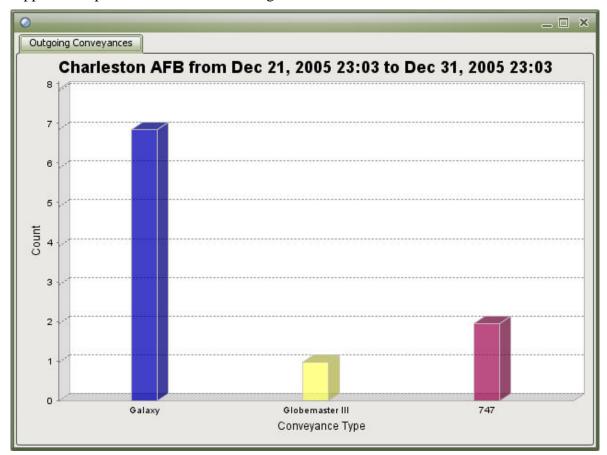


Figure 26: Departures from Charleston by conveyance type

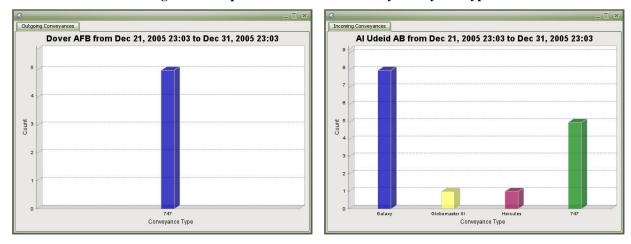


Figure 27: Departures from Dover

Figure 28: Departures from Al Udeid

Figures 26 to 28 show examples of conveyance departures from the Charleston, Dover and Al Udeid APODs, respectively. Similar reports are available for cargo transfers by date (Figures 29 to 30) in terms of what was lifted yesterday, the current inventory, and what is planned to be lifted during the next 72 hours. In this way the user is able to determine the expected volume of

shipments from any particular APOD on a daily basis. The dates selected for the example bar chart reports shown in Figures 29 and 30 are December 23 to 26, 2005.

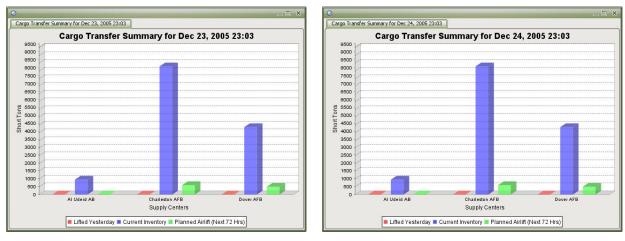


Figure 29: Typical cargo transfer history, status, and 72-hour projections

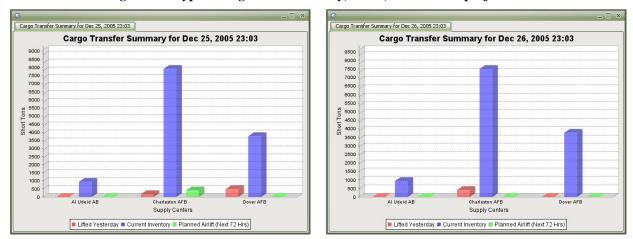


Figure 30: Typical cargo transfer history, status, and 72-hour projections

Again, these reports are intended to be examples of the kind of information that can be made available by TRANSWAY. The development team will be guided by feedback from users in future development cycles. The reporting capabilities of the system can be easily extended in any direction within the constraints of data availability.

Integration with SM21 Web Portal

It is planned to integrate TRANSWAY with the SM21 Web Portal that is being developed by other SM21 Project team members (i.e., Steve Carson).

The TRANSWAY Toolsets in an Experimental Exercise

The proposed experimental demonstration of the SM21 Project follows a demonstration of the concepts of an Efficient Marine Terminal (EMT) and Agile Port System (APS) that was conducted at the Port of Tacoma, Washington, in 2003 within the context of a commercial-public transportation environment. EMT represented the marine terminal component of a postulated Efficient Marine/Rail Intermodal Interface (EMRII) system. The demonstration suggested that full implementation of the EMRII concepts and associated processes could conceivably achieve operating cost savings of approximately 40%.

The purpose of the SM21 demonstration planned for sometime during the first half of 2007 is to validate the findings of the 2003 demonstration with a full-scale implementation of the entire EMRII system. Specifically, it is proposed to utilize an integrated SM21 system platform in support of the deployment of a Brigade Combat Team from Fort Lewis to the Port of Tacoma through the commercial-public transportation corridor. The demonstration objectives include:

- Explore the integration requirements of military, commercial, and public transportation needs and expectations within the constraints of a commercial-public transportation corridor.
- Address the ability of a marine terminal to accommodate military load-out operations while minimizing disruption to commercial operations.
- Minimize the area of terminal real estate required during ship loading operations by reducing the total staging area requirement to no more than two acres.
- Conduct the military deployment operations through a commercial terminal in parallel with commercial container ship unloading and loading operations.
- Provide the ability to plan, track, and dynamically re-plan the force deployment from the garrison to the port.

As stated in the after-action report of the 2003 demonstration, it is proposed to: "...to construct and demonstrate a dynamic force deployment execution process planning that allows for dynamic re-planning of the PPP (Power Projection Platform) to strategic port movement of forces ..." (Savacool 2006).

The Exercise Scenario

It is proposed to move an Army Brigade Combat Team (BCT), comprising approximately 3,000 soldiers with their organic equipment assets, from Ft. Lewis to the Port of Tacoma. Since Ft Lewis is located less than 20 miles from the Port, the movement will utilize truck convoys. The objective of the exercise is to accomplish this military movement as expeditiously and efficiently as possible with minimum disruption of vehicular traffic in the public transportation corridor and minimum impact on normal commercial port operations. Efficiencies and economies are expected to be achieved by:

A. Utilizing to the extent possible commercial-of-the-shelf (COTS) and government-of-the-shelf (GOTS) software, integrated to facilitate the flow of data and thereby ensure the availability of a common operational picture throughout the exercise. This will

- require the seamless exchange of data between multiple software systems during the movement.
- B. Integrating existing military data feeds (e.g., TCAIMS-II) into the data flow, so that the data used in the SM21 system environment are compatible with and representative of standard military logistic data. This will require the fusion of data received from separate military and commercial sources.
- C. Emphasizing pre-execution planning through early examination of data, anticipation of problem areas and potential failure points, and the development of contingency plans.
- D. Considering the vehicular traffic patterns in the affected portions of the public-commercial traffic corridor during the earliest planning stages.
- E. Considering the potential influence of the movement on the normal commercial port activities, and vice versa, during the earliest planning stages.
- F. Having available intelligent re-planning tools that will allow operators to prepare alternative plans in near real-time when unforeseen events occur during the execution phase.
- G. Reducing the marshalling yard footprint(s) required at Ft Lewis and at the Port of Tacoma, to the extent possible.
- H. Considering the loading sequence of the ship(s) at the port during planning of the marshalling yard(s) at Ft Lewis, the order of trucks and convoys, and the staging of equipment at the Port.
- I. Maintaining in-transit visibility throughout the movement from the marshalling yard(s) at Fort Lewis to the final location of the equipment and supplies on-board ship.
- J. Planning and executing concurrent ship loading operations at the Port, so that the loading time will be reduced through parallel loading operations performed by multiple Stevedore gangs on the same ship.
- K. Increasing the load-planning efficiency of truck and ship conveyances in terms of decreased plan preparation time, reduced human resource requirements, and superior storage space utilization.
- L. Increasing the security and force protection aspects of the movement through better planning, tighter control of processes, continuous monitoring and in-transit visibility, and faster reaction to unforeseen events.

The exercise is planned to be conducted under real world conditions during an actual force deployment, with normal coordination and controlling roles played by the military chain of command, the operational personnel of the Army's Surface Deployment and Distribution Command (SDDC)¹, civilian supervisory port personnel, and local law enforcement authorities.

¹ The Surface Deployment and Distribution Command (SDDC) serves concurrently as a subordinate command of the Army and a component command of USTRANSCOM.

Applying the Capabilities of the TRANSWAY Toolset

Utilizing the interoperability between TRANSWAY and the Integrated Computerized Deployment System (ICODES), both TRANSWAY and ICODES will be employed as an integrated adaptive toolset during the proposed SM21 exercise. The capabilities of this integrated toolset are described in more detail in a previous SM21 report entitled: "Adaptive Software for Simulation Demonstration Support" submitted in early October 2006. In summary, the principal capabilities will be applied in the following functional areas:

- Exchanging data with several existing military data feeds (i.e., TCAIMS-II, WPS, IBS (receiving only), and MDSS-II).
- Preparing objectified spatial representations of marshalling yards, conveyances, and transportation routes (within a geo-spatial reference frame).
- Preparing staging plans and conveyance load-plans, with consideration of data integrity, storage area accessibility, hazardous material requirements, and trim and stability concerns in the case of ships only.
- Planning of delivery routes involving roads, seaways, and air channels.
- Rapidly re-planning load-plans and delivery plans in near real-time under emergency and extenuating circumstances.
- Merging cargo list changes received from military data feeds with existing cargo data, on a continuous basis throughout the conduct of the exercise.
- Exporting the cargo data contained in final load-plans to military systems through the same data feeds that were previously employed to import cargo data into ICODES.

These capabilities are available to be utilized within the integrated SM21 software environment during the exercise in support of the following operational sequences and functional activities:

- 1. Importing an initial cargo list from the TCAIMS-II, WPS or MDSS-II military data feeds.
- 2. Validating the integrity and completeness of the imported cargo list by comparison with multiple reference libraries.
- 3. Preparing an objectified spatial representation of the marshalling yards at Ft Lewis and at the Port of Tacoma.
- 4. Preparing cargo staging plans for the marshalling yards at Ft Lewis and the Port of Tacoma.
- 5. Capturing data pertaining to cargo with PDAs utilizing barcode scanning devices in (secure) wireless communication environments.
- 6. Preparing an objectified spatial representation of one or more types of trucks.
- 7. Preparing load-plans for trucks and truck convoys.
- 8. Preparing delivery plans for the movement of truck convoys from Ft Lewis to the Port of Tacoma.

- 9. Re-planning delivery routes in case of events that require alternative delivery plans.
- 10. Preparing load-plans for the embarkation of cargo onto ships.
- 11. Re-planning loads on conveyances during execution in case of events that require alternative load-plans.
- 12. Merging cargo data imported from external military data feeds with existing cargo data in the SM21 system environment.
- 13. Exporting final load-plan data from the SM21 system environment to military systems via TCAIMS-II, WPS or MDSS-II.
- 14. Providing visual access to load-plan information throughout the exercise via web-based user-interfaces.
- 15. Providing geo-spatial mapping capabilities for the visualization of infrastructure and routes from a global view down to street level detail.

References:

Savacool E. (2006); 'Military Agile Port Demonstration Preplanning Overview'; CCDoTT Report, California State University, Long Beach, California, June 28.

TRANSWAY Data Dictionary

| TRANSWAY Name | Туре | Data Domain | TRANSWAY Description |
|-----------------------|-------------|---|--|
| Person/ Passenger: | | | |
| SSN | string | Any string | Social security number of person who is required to be loaded onto a conveyance as a passenger. |
| lastName | string | Any string | Last name of passenger. |
| firstName | string | Any string | First name of passenger. |
| middleName | string | Any string | Middle name of passenger. |
| dateOfBirth | integer | numeric | Date of birth of passenger. |
| bloodType | enumeration | APOS, BPOS, ABPOS, and OPOS | Blood type of passenger. |
| gender | enumeration | male, female, unknown | The adjusted height of the parent for a particular association as a result of taking the dimensions of the children. |
| height | float | numeric | Height of passenger in inches (in). |
| weight | float | numeric | Weight of passenger in pounds (lb). |
| Alerts: | | | |
| type | enumeration | General, supply shortfall, conveyance shortfall, plan invalid | Type of alert provided by an agent. |
| priority | enumeration | Low, medium, high | Priority of the alert generated by an agent. |
| summaryMessage | string | Any string | Explanatory message generated by agent in conjunction with an alert. |
| acknowledged | boolean | Acknowledgement (true/false) | Status of acknowledgement of agent alert by user. |
| Node: | | | |
| type | enumeration | SSA, POD, APOD, SPOD, POE, APOE, SPOE | Node type. |

| earliestAllowableTr ansportDeparture | integer | numeric | Earliest time at which conveyance is able or authorized to depart. |
|---|-------------|--|---|
| latestAllowableTran sportDeparture | integer | numeric | Latest time at which conveyance is able to depart to meet future deadlines. |
| MOGw | integer | numeric | Maximum on ground – working (maximum number of aircraft that can be loaded or unloaded at a particular APOD/E at any one time). |
| MOGp | integer | numeric | Maximum on ground – parking (maximum number of aircraft that can be parked at a particular APOD/E at any one time). |
| throughput | float | numeric | Quantity of cargo that can be moved out of the node in pounds per hour (lb/hr). |
| fuelQuantity | float | numeric | Amount of fuel holding capacity. |
| holdingCapacity | float | numeric | Amount of cargo that can be stored at node. |
| Route: | | | |
| routeType | enumeration | paved road, unpaved road, air channel, water channel | Type of air or surface route. |
| length | float | numeric | Length of route (or route leg) in nautical miles (nm). |
| locationA | float | Struct | Location of start node of route in terms of latitude/longitude/altitude. |
| locationB | float | Struct | Location of end node of route in terms of latitude/longitude/altitude. |
| Impediment: | | | |
| type | enumeration | unknown, weather, attack, explosion | Type of impediment (however, only the weather impediment is implemented in Version 1.0). |
| degree | enumeration | Low, medium, high | Overall severity of impediment. |
| precipitation | enumeration | none, hail, snow | Type of precipitation impediment. |
| obstructions | enumeration | None, light, moderate, heavy | Degree of obstruction due to impediment. |
| duration | float | numeric | Time period during which the impediment is in effect in hours (hr). |

| speed | float | numeric | Speed at which weather front is moving in nautical miles (nm). |
|-----------------------|-------------|-------------------------------------|---|
| bearing | float | numeric | Direction in which weather front is moving. |
| Conveyance: | | | |
| position | float | Struct | Position of conveyance in terms of latitude/longitude/altitude. |
| speed | float | numeric | Current speed of conveyance in knots (kph). |
| range | float | numeric | Total distance conveyance can travel regardless of refueling need. |
| homeLocation | float | Struct | Conveyance home base in terms of latitude/longitude/altitude. |
| loadTime | float | numeric | Standard time to load conveyance. |
| unloadTime | float | numeric | Standard time to unload conveyance. |
| maxWeigthCapacit y | float | numeric | Maximum weight conveyance can operate with. |
| maxPalletCapacity | float | numeric | Maximum number of pallets that can be loaded onto conveyance. |
| type | enumeration | truck, vessel, rotary, winged, rail | Type of conveyance (however, rail is not implemented in Version 1.0). |
| inflightRefuel | boolean | capable (true/false) | Whether aircraft conveyance can be refueled in flight. |
| length | float | numeric | Maximum standard length of conveyance in inches (in). |
| width | float | numeric | Maximum standard width of conveyance in inches (in). |
| height. | float | numeric | Maximum standard height of conveyance in inches (in). |
| weight | float | numeric | Maximum standard weight of unloaded conveyance. |
| fuelConsumption | float | numeric | Fuel consumption of conveyance at cruising speed. |
| <u> </u> | • | | |

| | | | · |
|--------------------------------------|-------------|--|---|
| location | float | Struct | Current location of conveyance in terms of latitude/longitude/altitude. |
| maxContainer | integer | numeric | Maximum number of containers that can be loaded onto conveyance. |
| militaryCivilian | enumeration | military, civilian | Whether conveyance has military or civilian ownership. |
| crewSize | integer | numeric | Number of persons needed to operate conveyance. |
| unrefueledRange | float | numeric | Maximum standard distance conveyance can travel without refueling. |
| Cargo: | | | |
| supplyClass | enumeration | I, II, II, III, IV, V, VI, VII, VIII, IX | Supply Class (however, only Classes I, V, and IX (partial) are implemented in Version 1.0). |
| unitMeasure | enumeration | Each, box, case | Packaging configuration of the cargo item. |
| packageQuantiy | integer | numeric | Number of items per package. |
| length | float | numeric | Maximum length of package in inches (in). |
| width | float | numeric | Maximum width of package in inches (in). |
| height | float | numeric | Maximum height of package in inches (in). |
| weight | float | numeric | Maximum weight of package in pounds (lb). |
| NSN | string | Any string (13 characters) | National Stock Number. |
| commodityCode | string | Any string | Commodity code of cargo item. |
| Requirement/Req uest for Supples: | | | |
| cargoList | (n/a) | (n/a) | List of requested types of supply items. |
| quantity | integer | numeric | Quantity of each type of supply item requested. |

| locationDestination | float | Struct | Location of delivery destination in terms of latitude/longitude/altitude. |
|---------------------|-------------|-----------------------------------|--|
| ETA | integer | numeric | Earliest Time of Arrival at delivery destination. |
| LTA | integer | numeric | Latest Time of Arrival at delivery destination. |
| priority | enumeration | Low, medium, high | Priority assigned to request for supplies. |
| Pallet: | | | |
| location | float | Struct | Current location of pallet in terms of latitude/longitude/altitude. |
| type | enumeration | 463L, standard wood, factory wood | Type of pallet (however, only the 463L pallet type is implemented in Version 1.0). |
| quantity | integer | numeric | Quantity of this type of pallet available at the location. |
| totalWeight | float | numeric | Holding capacity of pallet in pounds (lb). |
| totalHeight | float | numeric | Maximum allowable height of pallet and contents in inches (in). |
| palletCondition | enumeration | serviceable, repairable, unusable | Condition of pallet. |
| length | float | numeric | Maximum length of pallet in inches (in). |
| width | float | numeric | Maximum width of pallet in inches (in). |
| height | float | numeric | Maximum height of empty pallet in inches (in). |
| weight | float | numeric | Maximum weight of empty pallet in pounds (lb). |
| weightNetting | float | numeric | Maximum weight of netting and tie downs in pounds (lb). |
| volume | float | numeric | Maximum volume of pallet and contents in cubic feet (cf). |
| stackingHeight | integer | numeric | Maximum number of pallets that can be stacked. |
| | 1 | 1 | |

| numberContainer | integer | numeric | Maximum number of pallets allowed in a container. |
|--------------------|-------------|-----------------------------------|--|
| Container: | | | |
| location | float | Struct | Current location of container in terms of latitude/longitude/altitude. |
| type | enumeration | Standard, dry, rack, reefer | Type of container. |
| quantity | integer | numeric | Quantity of this type of container available at the location. |
| totalWeight | float | numeric | Holding capacity of container in pounds (lb). |
| containerCondition | enumeration | serviceable, repairable, unusable | Condition of container. |
| lengthOS | float | numeric | Maximum external length of container in inches (in). |
| widthOS | float | numeric | Maximum external width of container in inches (in). |
| heightOS | float | numeric | Maximum external height of container in inches (in). |
| weight | float | numeric | Maximum weight of empty container in pounds (lb). |
| volumeOS | float | numeric | Maximum external volume of container in cubic feet (cf). |
| volumeHolding | float | numeric | Maximum internal volume of container in cubic feet (cf). |
| lengthHolding | integer | numeric | Maximum internal length of container in inches (in). |
| widthHolding | float | numeric | Maximum internall width of container in inches (in). |
| heightHolding | float | numeric | Maximum internall height of container in inches (in). |
| stackingHeight | integer | numeric | Maximum number of containers that can be stacked. |
| | | | |